NAG Toolbox for MATLAB

d03pd

1 Purpose

d03pd integrates a system of linear or nonlinear parabolic partial differential equations (PDEs) in one space variable. The spatial discretization is performed using a Chebyshev C^0 collocation method, and the method of lines is employed to reduce the PDEs to a system of ordinary differential equations (ODEs). The resulting system is solved using a backward differentiation formula method.

2 Syntax

```
[ts, u, x, rsave, isave, ind, user, cwsav, lwsav, iwsav, rwsav, ifail] =
d03pd(m, ts, tout, pdedef, bndary, u, xbkpts, npoly, uinit, acc, rsave,
isave, itask, itrace, ind, cwsav, lwsav, iwsav, rwsav, 'npde', npde,
'nbkpts', nbkpts, 'npts', npts, 'lrsave', lrsave, 'lisave', lisave,
'user', user)
```

3 Description

d03pd integrates the system of parabolic equations:

$$\sum_{j=1}^{\mathbf{npde}} P_{i,j}\frac{\partial U_j}{\partial t} + Q_i = x^{-m}\frac{\partial}{\partial x}(x^m R_i), \qquad i = 1,2,\ldots,\mathbf{npde}, \qquad a \le x \le b, t \ge t_0, \tag{1}$$

where $P_{i,j}$, Q_i and R_i depend on x, t, U, U_x and the vector U is the set of solution values

$$U(x,t) = \left[U_1(x,t),\ldots,U_{\mathbf{npde}}(x,t)\right]^{\mathrm{T}}, \tag{2}$$

and the vector U_x is its partial derivative with respect to x. Note that $P_{i,j}$, Q_i and R_i must not depend on $\dfrac{\partial U}{\partial t}$.

The integration in time is from t_0 to t_{out}, over the space interval $a \le x \le b$, where $a = x_1$ and $b = x_{\mathbf{nbkpts}}$ are the leftmost and rightmost of a user-defined set of break points $x_1, x_2, \ldots, x_{\mathbf{nbkpts}}$. The co-ordinate system in space is defined by the value of m; $m = 0$ for Cartesian co-ordinates, $m = 1$ for cylindrical polar co-ordinates and $m = 2$ for spherical polar co-ordinates.

The system is defined by the functions $P_{i,j}$, Q_i and R_i which must be specified in a user-supplied (sub)program **pdedef**.

The initial values of the functions $U(x,t)$ must be given at $t = t_0$, and must be specified in a user-supplied (sub)program **uinit**.

The functions R_i, for $i = 1,2,\ldots,\mathbf{npde}$, which may be thought of as fluxes, are also used in the definition of the boundary conditions for each equation. The boundary conditions must have the form

$$\beta_i(x,t)R_i(x,t,U,U_x) = \gamma_i(x,t,U,U_x), \qquad i = 1,2,\ldots,\mathbf{npde}, \tag{3}$$

where $x = a$ or $x = b$.

The boundary conditions must be specified in a user-supplied (sub)program **bndary**. Thus, the problem is subject to the following restrictions:

(i) $t_0 < t_{\mathrm{out}}$, so that integration is in the forward direction;

(ii) $P_{i,j}$, Q_i and the flux R_i must not depend on any time derivatives;

(iii) the evaluation of the functions $P_{i,j}$, Q_i and R_i is done at both the break points and internally selected points for each element in turn, that is $P_{i,j}$, Q_i and R_i are evaluated twice at each break point. Any

discontinuities in these functions **must** therefore be at one or more of the break points $x_1, x_2, \ldots, x_{\mathbf{nbkpts}}$;

(iv) at least one of the functions $P_{i,j}$ must be nonzero so that there is a time derivative present in the problem;

(v) if $m > 0$ and $x_1 = 0.0$, which is the left boundary point, then it must be ensured that the PDE solution is bounded at this point. This can be done by either specifying the solution at $x = 0.0$ or by specifying a zero flux there, that is $\beta_i = 1.0$ and $\gamma_i = 0.0$. See also Section 8.

The parabolic equations are approximated by a system of ODEs in time for the values of U_i at the mesh points. This ODE system is obtained by approximating the PDE solution between each pair of break points by a Chebyshev polynomial of degree **npoly**. The interval between each pair of break points is treated by d03pd as an element, and on this element, a polynomial and its space and time derivatives are made to satisfy the system of PDEs at **npoly** $-$ 1 spatial points, which are chosen internally by the code and the break points. In the case of just one element, the break points are the boundaries. The user-defined break points and the internally selected points together define the mesh. The smallest value that **npoly** can take is one, in which case, the solution is approximated by piecewise linear polynomials between consecutive break points and the method is similar to an ordinary finite element method.

In total there are $(\mathbf{nbkpts} - 1) \times \mathbf{npoly} + 1$ mesh points in the spatial direction, and $\mathbf{npde} \times ((\mathbf{nbkpts} - 1) \times \mathbf{npoly} + 1)$ ODEs in the time direction; one ODE at each break point for each PDE component and $(\mathbf{npoly} - 1)$ ODEs for each PDE component between each pair of break points. The system is then integrated forwards in time using a backward differentiation formula method.

4 References

Berzins M 1990 Developments in the NAG Library software for parabolic equations *Scientific Software Systems* (ed J C Mason and M G Cox) 59–72 Chapman and Hall

Berzins M and Dew P M 1991 Algorithm 690: Chebyshev polynomial software for elliptic-parabolic systems of PDEs *ACM Trans. Math. Software* **17** 178–206

Zaturska N B, Drazin P G and Banks W H H 1988 On the flow of a viscous fluid driven along a channel by a suction at porous walls *Fluid Dynamics Research* **4**

5 Parameters

5.1 Compulsory Input Parameters

1: **m – int32 scalar**

The co-ordinate system used:

m $= 0$

Indicates Cartesian co-ordinates.

m $= 1$

Indicates cylindrical polar co-ordinates.

m $= 2$

Indicates spherical polar co-ordinates.

Constraint: $0 \leq \mathbf{m} \leq 2$.

2: **ts – double scalar**

The initial value of the independent variable t.

Constraint: **ts** $<$ **tout**.

3: **tout – double scalar**

The final value of t to which the integration is to be carried out.

4: **pdedef – string containing name of m-file**

pdedef must compute the values of the functions $P_{i,j}$, Q_i and R_i which define the system of PDEs. The functions may depend on x, t, U and U_x and must be evaluated at a set of points.

```
[p, q, r, ires, user] = pdedef(npde, t, x, nptl, u, ux, ires, user)
```

Input Parameters

1: **npde – int32 scalar**

The number of PDEs in the system.

2: **t – double scalar**

The current value of the independent variable t.

3: **x(nptl) – double array**

Contains a set of mesh points at which $P_{i,j}$, Q_i and R_i are to be evaluated. $\mathbf{x}(1)$ and $\mathbf{x}(\mathbf{nptl})$ contain successive user-supplied break points and the elements of the array will satisfy $\mathbf{x}(1) < \mathbf{x}(2) < \cdots < \mathbf{x}(\mathbf{nptl})$.

4: **nptl – int32 scalar**

The number of points at which evaluations are required (the value of **npoly** + 1).

5: **u(npde,nptl) – double array**

$\mathbf{u}(i,j)$ contains the value of the component $U_i(x,t)$ where $x = \mathbf{x}(j)$, for $i = 1, 2, \ldots,$ **npde** and $j = 1, 2, \ldots,$ **nptl**.

6: **ux(npde,nptl) – double array**

$\mathbf{ux}(i,j)$ contains the value of the component $\dfrac{\partial U_i(x,t)}{\partial x}$ where $x = \mathbf{x}(j)$, for $i = 1, 2, \ldots,$ **npde** and $j = 1, 2, \ldots,$ **nptl**.

7: **ires – int32 scalar**

Set to -1 or 1.

Should usually remain unchanged. However, you may set **ires** to force the integration function to take certain actions as described below:

ires $= 2$

Indicates to the integrator that control should be passed back immediately to the calling (sub)program with the error indicator set to **ifail** $= 6$.

ires $= 3$

Indicates to the integrator that the current time step should be abandoned and a smaller time step used instead. You may wish to set **ires** $= 3$ when a physically meaningless input or output value has been generated. If you consecutively set **ires** $= 3$, then d03pd returns to the calling (sub)program with the error indicator set to **ifail** $= 4$.

8: **user – Any MATLAB object**

pdedef is called from d03pd with **user** as supplied to d03pd

Output Parameters

1: **p(npde,npde,nptl) – double array**

$\mathbf{p}(i,j,k)$ must be set to the value of $P_{i,j}(x,t,U,U_x)$ where $x = \mathbf{x}(k)$, for $i,j = 1,2,\ldots,$ **npde** and $k = 1,2,\ldots,$ **nptl**.

2: **q(npde,nptl) – double array**

$\mathbf{q}(i,j)$ must be set to the value of $Q_i(x,t,U,U_x)$ where $x = \mathbf{x}(j)$, for $i = 1,2,\ldots,$ **npde** and $j = 1,2,\ldots,$ **nptl**.

3: **r(npde,nptl) – double array**

$\mathbf{r}(i,j)$ must be set to the value of $R_i(x,t,U,U_x)$ where $x = \mathbf{x}(j)$, for $i = 1,2,\ldots,$ **npde** and $j = 1,2,\ldots,$ **nptl**.

4: **ires – int32 scalar**

Set to -1 or 1.

Should usually remain unchanged. However, you may set **ires** to force the integration function to take certain actions as described below:

ires $= 2$

Indicates to the integrator that control should be passed back immediately to the calling (sub)program with the error indicator set to **ifail** $= 6$.

ires $= 3$

Indicates to the integrator that the current time step should be abandoned and a smaller time step used instead. You may wish to set **ires** $= 3$ when a physically meaningless input or output value has been generated. If you consecutively set **ires** $= 3$, then d03pd returns to the calling (sub)program with the error indicator set to **ifail** $= 4$.

5: **user – Any MATLAB object**

pdedef is called from d03pd with **user** as supplied to d03pd

5: **bndary – string containing name of m-file**

bndary must compute the functions β_i and γ_i which define the boundary conditions as in equation (3).

```
[beta, gamma, ires, user] = bndary(npde, t, u, ux, ibnd, ires, user)
```

Input Parameters

1: **npde – int32 scalar**

The number of PDEs in the system.

2: **t – double scalar**

The current value of the independent variable t.

3: **u(npde) – double array**

u(i) contains the value of the component $U_i(x,t)$ at the boundary specified by **ibnd**, for $i = 1,2,\ldots,$ **npde**.

4: **ux(npde) – double array**

ux(i) contains the value of the component $\dfrac{\partial U_i(x,t)}{\partial x}$ at the boundary specified by **ibnd**, for $i = 1,2,\ldots,$ **npde**.

5: **ibnd – int32 scalar**

Specifies which boundary conditions are to be evaluated.

ibnd $= 0$

bndary must set up the coefficients of the left-hand boundary, $x = a$.

ibnd $\neq 0$

bndary must set up the coefficients of the right-hand boundary, $x = b$.

6: **ires – int32 scalar**

Set to -1 or 1.

Should usually remain unchanged. However, you may set **ires** to force the integration function to take certain actions as described below:

ires $= 2$

Indicates to the integrator that control should be passed back immediately to the calling (sub)program with the error indicator set to **ifail** $= 6$.

ires $= 3$

Indicates to the integrator that the current time step should be abandoned and a smaller time step used instead. You may wish to set **ires** $= 3$ when a physically meaningless input or output value has been generated. If you consecutively set **ires** $= 3$, then d03pd returns to the calling (sub)program with the error indicator set to **ifail** $= 4$.

7: **user – Any MATLAB object**

bndary is called from d03pd with **user** as supplied to d03pd

Output Parameters

1: **beta(npde) – double array**

beta(i) must be set to the value of $\beta_i(x,t)$ at the boundary specified by **ibnd**, for $i = 1,2,\ldots,$ **npde**.

2: **gamma(npde) – double array**

gamma(i) must be set to the value of $\gamma_i(x,t,U,U_x)$ at the boundary specified by **ibnd**, for $i = 1,2,\ldots,$ **npde**.

3: **ires – int32 scalar**

Set to -1 or 1.

Should usually remain unchanged. However, you may set **ires** to force the integration function to take certain actions as described below:

ires $= 2$

Indicates to the integrator that control should be passed back immediately to the calling (sub)program with the error indicator set to **ifail** $= 6$.

ires $= 3$

Indicates to the integrator that the current time step should be abandoned and a smaller time step used instead. You may wish to set **ires** $= 3$ when a physically meaningless input or output value has been generated. If you consecutively set **ires** $= 3$, then d03pd returns to the calling (sub)program with the error indicator set to **ifail** $= 4$.

4: **user – Any MATLAB object**

bndary is called from d03pd with **user** as supplied to d03pd

6: **u**(**npde**,**npts**) **– double array**

If **ind** $= 1$ the value of **u** must be unchanged from the previous call.

7: **xbkpts**(**nbkpts**) **– double array**

The values of the break points in the space direction. **xbkpts**(1) must specify the left-hand boundary, a, and **xbkpts**(**nbkpts**) must specify the right-hand boundary, b.

Constraint: **xbkpts**$(1) <$ **xbkpts**$(2) < \cdots <$ **xbkpts**(**nbkpts**).

8: **npoly – int32 scalar**

The degree of the Chebyshev polynomial to be used in approximating the PDE solution between each pair of break points.

Constraint: $1 \leq$ **npoly** ≤ 49.

9: **uinit – string containing name of m-file**

uinit must compute the initial values of the PDE components $U_i(x_j, t_0)$, for $i = 1, 2, \ldots,$ **npde** and $j = 1, 2, \ldots,$ **npts**.

```
[u, user] = uinit(npde, npts, x, user)
```

Input Parameters

1: **npde – int32 scalar**

The number of PDEs in the system.

2: **npts – int32 scalar**

the number of mesh points in the interval $[a, b]$.

3: **x**(**npts**) **– double array**

x(j), contains the values of the jth mesh point, for $j = 1, 2, \ldots,$ **npts**.

4: **user – Any MATLAB object**

uinit is called from d03pd with **user** as supplied to d03pd

Output Parameters

1: **u(npde,npts) – double array**

u(i,j) must be set to the initial value $U_i(x_j,t_0)$, for $i = 1,2,\ldots,$ **npde** and $j = 1,2,\ldots,$ **npts**.

2: **user – Any MATLAB object**

uinit is called from d03pd with **user** as supplied to d03pd

10: **acc – double scalar**

A positive quantity for controlling the local error estimate in the time integration. If $E(i,j)$ is the estimated error for U_i at the jth mesh point, the error test is:

$$|E(i,j)| = \textbf{acc} \times (1.0 + |\mathbf{u}(i,j)|).$$

Constraint: **acc** > 0.0.

11: **rsave(lrsave) – double array**

If **ind** $= 0$, **rsave** need not be set on entry.

If **ind** $= 1$, **rsave** must be unchanged from the previous call to the function because it contains required information about the iteration.

12: **isave(lisave) – int32 array**

If **ind** $= 0$, **isave** need not be set on entry.

If **ind** $= 1$, **isave** must be unchanged from the previous call to the function because it contains required information about the iteration. In particular:

isave(1)

Contains the number of steps taken in time.

isave(2)

Contains the number of residual evaluations of the resulting ODE system used. One such evaluation involves computing the PDE functions at all the mesh points, as well as one evaluation of the functions in the boundary conditions.

isave(3)

Contains the number of Jacobian evaluations performed by the time integrator.

isave(4)

Contains the order of the last backward differentiation formula method used.

isave(5)

Contains the number of Newton iterations performed by the time integrator. Each iteration involves an ODE residual evaluation followed by a back-substitution using the LU decomposition of the Jacobian matrix.

13: **itask – int32 scalar**

Specifies the task to be performed by the ODE integrator.

itask $= 1$

Normal computation of output values **u** at $t =$ **tout**.

itask $= 2$

One step and return.

itask $= 3$

Stop at first internal integration point at or beyond $t =$ **tout**.

Constraint: $1 \leq$ **itask** ≤ 3.

14: **itrace – int32 scalar**

The level of trace information required from d03pd and the underlying ODE solver. **itrace** may take the value -1, 0, 1, 2 or 3.

itrace $= -1$

No output is generated.

itrace $= 0$

Only warning messages from the PDE solver are printed on the current error message unit (see x04aa).

itrace > 0

Output from the underlying ODE solver is printed on the current advisory message unit (see x04ab). This output contains details of Jacobian entries, the nonlinear iteration and the time integration during the computation of the ODE system.

If **itrace** < -1, then -1 is assumed and similarly if **itrace** > 3, then 3 is assumed.

The advisory messages are given in greater detail as **itrace** increases. You are advised to set **itrace** $= 0$, unless you are experienced with sub-chapter D02M/N.

15: **ind – int32 scalar**

Must be set to 0 or 1.

ind $= 0$

Starts or restarts the integration in time.

ind $= 1$

Continues the integration after an earlier exit from the function. In this case, only the parameters **tout** and **ifail** should be reset between calls to d03pd.

Constraint: $0 \leq$ **ind** ≤ 1.

16: **cwsav(10) – string array**

17: **lwsav(100) – logical array**

18: **iwsav(505) – int32 array**

19: **rwsav(1100) – double array**

5.2 Optional Input Parameters

1: **npde – int32 scalar**

Default: The dimension of the array **u**.

the number of PDEs in the system to be solved.

Constraint: **npde** ≥ 1.

2: **nbkpts – int32 scalar**

Default: The dimension of the array **xbkpts**.

the number of break points in the interval $[a, b]$.

Constraint: **nbkpts** ≥ 2.

3: **npts – int32 scalar**

Default: The dimension of the array **x**.

the number of mesh points in the interval $[a, b]$.

Constraint: **npts** $= (\mathbf{nbkpts} - 1) \times \mathbf{npoly} + 1$.

4: **lrsave – int32 scalar**

Default: The dimension of the array **rsave**.

Constraint: **lrsave** $\geq 11 \times \mathbf{npde} \times \mathbf{npts} + 50 + NWKRES + LENODE$, where $NWKRES = 3 \times (\mathbf{npoly} + 1)^2 + (\mathbf{npoly} + 1) \times \left(\mathbf{npde}^2 + 6 \times \mathbf{npde} + \mathbf{nbkpts} + 1\right) + 13 \times \mathbf{npde} + 5$, and $LENODE = \mathbf{npde} \times \mathbf{npts} \times (3 \times \mathbf{npde} \times (\mathbf{npoly} + 1) - 2)$.

5: **lisave – int32 scalar**

Default: The dimension of the array **isave**.

Constraint: **lisave** $\geq \mathbf{npde} \times \mathbf{npts} + 24$.

6: **user – Any MATLAB object**

user is not used by d03pd, but is passed to **pdedef**, **bndary** and **uinit**. Note that for large objects it may be more efficient to use a global variable which is accessible from the m-files than to use **user**.

5.3 Input Parameters Omitted from the MATLAB Interface

None.

5.4 Output Parameters

1: **ts – double scalar**

The value of t corresponding to the solution values in **u**. Normally **ts** $=$ **tout**.

2: **u(npde,npts) – double array**

$\mathbf{u}(i,j)$ will contain the computed solution at $t =$ **ts**.

3: **x(npts) – double array**

The mesh points chosen by d03pd in the spatial direction. The values of **x** will satisfy $\mathbf{x}(1) < \mathbf{x}(2) < \cdots < \mathbf{x}(\mathbf{npts})$.

4: **rsave(lrsave) – double array**

If **ind** $= 0$, **rsave** need not be set on entry.

If **ind** $= 1$, **rsave** must be unchanged from the previous call to the function because it contains required information about the iteration.

5: **isave**(**lisave**) – **int32 array**

If **ind** = 0, **isave** need not be set on entry.

If **ind** = 1, **isave** must be unchanged from the previous call to the function because it contains required information about the iteration. In particular:

isave(1)

Contains the number of steps taken in time.

isave(2)

Contains the number of residual evaluations of the resulting ODE system used. One such evaluation involves computing the PDE functions at all the mesh points, as well as one evaluation of the functions in the boundary conditions.

isave(3)

Contains the number of Jacobian evaluations performed by the time integrator.

isave(4)

Contains the order of the last backward differentiation formula method used.

isave(5)

Contains the number of Newton iterations performed by the time integrator. Each iteration involves an ODE residual evaluation followed by a back-substitution using the *LU* decomposition of the Jacobian matrix.

6: **ind – int32 scalar**

ind = 1.

7: **user – Any MATLAB object**

user is not used by d03pd, but is passed to **pdedef**, **bndary** and **uinit**. Note that for large objects it may be more efficient to use a global variable which is accessible from the m-files than to use **user**.

8: **cwsav**(**10**) – **string array**

9: **lwsav**(**100**) – **logical array**

10: **iwsav**(**505**) – **int32 array**

11: **rwsav**(**1100**) – **double array**

12: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **tout** $\leq$ **ts**,
or **tout** − **ts** is too small,
or **itask** $\neq$ 1, 2 or 3,
or **m** $\neq$ 0, 1 or 2,
or **m** $>$ 0 and **xbkpts**(1) $<$ 0.0,
or **npde** $<$ 1,
or **nbkpts** $<$ 2,

or **npoly** < 1 or **npoly** > 49,
or **npts** $\neq$ (**nbkpts** $- 1$) $\times$ **npoly** $+ 1$,
or **acc** ≤ 0.0,
or **ind** $\neq 0$ or 1,
or break points **xbkpts**(i) are not ordered,
or **lrsave** is too small,
or **lisave** is too small.

ifail $= 2$

The underlying ODE solver cannot make any further progress across the integration range from the current point $t =$ **ts** with the supplied value of **acc**. The components of **u** contain the computed values at the current point $t =$ **ts**.

ifail $= 3$

In the underlying ODE solver, there were repeated errors or corrector convergence test failures on an attempted step, before completing the requested task. The problem may have a singularity or **acc** is too small for the integration to continue. Integration was successful as far as $t =$ **ts**.

ifail $= 4$

In setting up the ODE system, the internal initialization function was unable to initialize the derivative of the ODE system. This could be due to the fact that **ires** was repeatedly set to 3 in at least one of the user-supplied (sub)programs **pdedef** or **bndary**, when the residual in the underlying ODE solver was being evaluated.

ifail $= 5$

In solving the ODE system, a singular Jacobian has been encountered. You should check your problem formulation.

ifail $= 6$

When evaluating the residual in solving the ODE system, **ires** was set to 2 in at least one of the user-supplied (sub)programs **pdedef** or **bndary**. Integration was successful as far as $t =$ **ts**.

ifail $= 7$

The value of **acc** is so small that the function is unable to start the integration in time.

ifail $= 8$

In one of the user-supplied (sub)programs **pdedef** or **bndary**, **ires** was set to an invalid value.

ifail $= 9$ (d02nn)

A serious error has occurred in an internal call to the specified function. Check the problem specification and all parameters and array dimensions. Setting **itrace** $= 1$ may provide more information. If the problem persists, contact NAG.

ifail $= 10$

The required task has been completed, but it is estimated that a small change in **acc** is unlikely to produce any change in the computed solution. (Only applies when you are not operating in one step mode, that is when **itask** $\neq 2$.)

ifail $= 11$

An error occurred during Jacobian formulation of the ODE system (a more detailed error description may be directed to the current error message unit).

ifail = 12

Not applicable.

ifail = 13

Not applicable.

ifail = 14

The flux function R_i was detected as depending on time derivatives, which is not permissible.

7 Accuracy

d03pd controls the accuracy of the integration in the time direction but not the accuracy of the approximation in space. The spatial accuracy depends on the degree of the polynomial approximation **npoly**, and on both the number of break points and on their distribution in space. In the time integration only the local error over a single step is controlled and so the accuracy over a number of steps cannot be guaranteed. You should therefore test the effect of varying the accuracy parameter, **acc**.

8 Further Comments

d03pd is designed to solve parabolic systems (possibly including elliptic equations) with second-order derivatives in space. The parameter specification allows you to include equations with only first-order derivatives in the space direction but there is no guarantee that the method of integration will be satisfactory for such systems. The position and nature of the boundary conditions in particular are critical in defining a stable problem.

The time taken depends on the complexity of the parabolic system and on the accuracy requested.

9 Example

d03pd_bndary.m

```
function [beta, gamma, ires, user] = bndary(npde, t, u, ux, ibnd, ires,
user)
  beta = zeros(npde, 1);
  gamma = zeros(npde, 1);

  if (ibnd == 0)
    beta(1) = 1;
    gamma(1) = 0;
    beta(2) = 0;
    gamma(2) = u(1) - 1;
  else
    beta(1) = 1;
    gamma(1) = 0;
    beta(2) = 0;
    gamma(2) = u(1) + 1;
  end
```

d03pd_pdedef.m

```
function [p, q, r, ires, user] = pdedef(npde, t, x, nptl, u, ux, ires,
user)
  p = zeros(npde, npde, nptl);
  q = zeros(npde, nptl);
  r = zeros(npde, nptl);

  for i = 1:nptl
    q(1,i) = u(2,i);
    q(2,i) = u(1,i)*ux(2,i) - ux(1,i)*u(2,i);
```

```
    r(1,i) = ux(1,i);
    r(2,i) = ux(2,i);
    p(1,1,i) = 0;
    p(1,2,i) = 0;
    p(2,1,i) = 0;
    p(2,2,i) = 1;
  end;
```

d03pd_uinit.m

```
function [u, user] = uinit(npde, npts, x, user)
  u = zeros(npde, npts);

  piby2 = pi/2;
  for i = 1:npts
    u(1,i) = -sin(piby2*x(i));
    u(2,i) = -piby2*piby2*u(1,i);
  end
```

```
m = int32(0);
ts = 0;
tout = 0.0001;
u = zeros(2, 28);
xbkpts = [-1;
     -0.7777777777777778;
     -0.5555555555555556;
     -0.3333333333333333;
     -0.1111111111111111;
     0.1111111111111111;
     0.3333333333333333;
     0.5555555555555556;
     0.7777777777777778;
     1];
npoly = int32(3);
acc = 0.0001;
rsave = zeros(2085, 1);
isave = zeros(80, 1, 'int32');
itask = int32(1);
itrace = int32(0);
ind = int32(0);
cwsav = {'', '', '', '', '', '', '', '', '', ''};
lwsav = false(100, 1);
iwsav = zeros(505, 1, 'int32');
rwsav = zeros(1100, 1);
[tsOut, uOut, x, rsaveOut, isaveOut, indOut, user, cwsavOut, ...
 lwsavOut, iwsavOut, rwsavOut, ifail] = ...
    d03pd(m, ts, tout, 'd03pd_pdedef', 'd03pd_bndary', u, xbkpts, npoly,
...
     'd03pd_uinit', acc, rsave, isave, itask, itrace, ind, cwsav, lwsav,
...
    iwsav, rwsav)
```

```
tsOut =
   1.0000e-04
uOut =
  Columns 1 through 7
    1.0000    0.9962    0.9659    0.9397    0.9063    0.8191    0.7660
   -2.4850   -2.4576   -2.3827   -2.3181   -2.2357   -2.0207   -1.8897
  Columns 8 through 14
    0.7071    0.5735    0.5000    0.4226    0.2588    0.1736    0.0871
   -1.7443   -1.4149   -1.2334   -1.0425   -0.6385   -0.4284   -0.2150
  Columns 15 through 21
   -0.0871   -0.1736   -0.2588   -0.4226   -0.5000   -0.5735   -0.7071
    0.2150    0.4284    0.6385    1.0425    1.2334    1.4149    1.7443
  Columns 22 through 28
   -0.7660   -0.8191   -0.9063   -0.9397   -0.9659   -0.9962   -1.0000
```

```
    1.8897    2.0207    2.2357    2.3181    2.3827    2.4576    2.4850
x =
   -1.0000
   -0.9444
   -0.8333
   -0.7778
   -0.7222
   -0.6111
   -0.5556
   -0.5000
   -0.3889
   -0.3333
   -0.2778
   -0.1667
   -0.1111
   -0.0556
    0.0556
    0.1111
    0.1667
    0.2778
    0.3333
    0.3889
    0.5000
    0.5556
    0.6111
    0.7222
    0.7778
    0.8333
    0.9444
    1.0000
rsaveOut =
     array elided
isaveOut =
     array elided
indOut =
           1
user =
     0
cwsavOut =
    ''
    ''
    [1x80 char]
    [1x80 char]
    [1x80 char]
    ''
    ''
    ''
    ''
    ''
lwsavOut =
     array elided
iwsavOut =
     array elided
rwsavOut =
     array elided
ifail =
           0
```